
entente Documentation

Metabolize

Sep 28, 2019

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CHAPTER 1

entente package

1.1 Submodules

1.1.1 entente.cli module

1.1.2 entente.composite module

`entente.composite.composite_meshes(mesh_paths)`

Create a composite as a vertex-wise average of several meshes in correspondence. Faces, groups, and other attributes are loaded from the first mesh given.

Parameters `mesh_paths` (*list*) – Paths of the meshes to average.

Returns The composite mesh.

Return type lace.mesh.Mesh

1.1.3 entente.equality module

Utilities related to mesh equality.

`entente.equality.attr_has_same_shape(first_obj, second_obj, attr)`

Given two objects, check if the given arraylike attributes of those objects have the same shape. If one object has an attribute value of `None`, the other must too.

Parameters

- `first_obj` (*obj*) – A object with an arraylike `attr` attribute.
- `second_obj` (*obj*) – Another object with an arraylike `attr` attribute.
- `attr` (*str*) – The name of the attribute to test.

Returns *True* if attributes are the same shape

Return type bool

`entente.equality.attr_is_equal(first_obj, second_obj, attr)`

Given two objects, check if the given arraylike attributes of those objects are equal. If one object has an attribute value of `None`, the other must too.

Parameters

- **first_obj** (`obj`) – A object with an arraylike `attr` attribute.
- **second_obj** (`obj`) – Another object with an arraylike `attr` attribute.
- **attr** (`str`) – The name of the attribute to test.

Returns `True` if attributes are equal

Return type `bool`

`entente.equality.have_same_topology(first_mesh, second_mesh)`

Given two meshes, check if they have the same vertex count and same faces. In other words, check if they have the same topology.

Parameters

- **first_mesh** (`lace.mesh.Mesh`) – A mesh.
- **second_mesh** (`lace.mesh.Mesh`) – Another mesh.

Returns `True` if meshes have the same topology

Return type `bool`

1.1.4 entente.landmarks module

1.1.5 entente.restore_correspondence module

`entente.restore_correspondence.find_correspondence(a, b, atol=0.0001, all.must.match=True, ret.unmatched.b=False, progress=True)`

Given $a[0], a[1], \dots, a[k]$ and $b[0], b[1], \dots, b[j]$, match each element of a to the corresponding element of b .

When `all.must.match` is `True` a and b must contain the same set of elements. $b[\text{find_correspondence}(a, b)]$ equals a . Otherwise, return `-1` for elements with no match in b .

Parameters

- **a** (`np.arraylike`) – $k \times n$ array.
- **b** (`np.arraylike`) – $j \times n$ array.
- **atol** (`float`) – Match tolerance.
- **all.must.match** (`bool`) – When `True`, a and b must contain the same elements.
- **ret.unmatched.b** (`bool`) – When `True`, return a tuple which also contains the indices of b which were not matched.
- **progress** (`bool`) – When `True`, show a progress bar.

Returns Indices of b as $k \times 1$

Return type `np.ndarray`

Note: This relies on a brute-force algorithm.

For the interpretation of *atol*, see documentation for *np.isclose*.

```
entente.restore_correspondence.restore_correspondence(shuffled_mesh,      reference_mesh,      atol=0.0001,      progress=True)
```

Given a reference mesh, reorder the vertices of a shuffled copy to restore correspondence with the reference mesh. The vertex set of the shuffled mesh and reference mesh must be equal within *atol*. Mutate *reference_mesh*. Ignore faces but preserves their integrity.

Parameters

- **reference_mesh** (*lace.mesh.Mesh*) – A mesh with the vertices in the desired order.
- **shuffled_mesh** (*lace.mesh.Mesh*) – A mesh with the same vertex set as *reference_mesh*.
- **progress** (*bool*) – When *True*, show a progress bar.

Returns *vx1* which maps old vertices in *shuffled_mesh* to new.

Return type *np.ndarray*

Note: This was designed to assist in extracting face ordering and groups from a *shuffled_mesh* that “work” with *reference_mesh*, so the face ordering and groups can be used with different vertices.

It relies on a brute-force algorithm.

1.1.6 entente.shuffle module

```
entente.shuffle.shuffle_faces(mesh)
```

Shuffle the mesh’s face ordering. The mesh is mutated.

Parameters **mesh** (*lace.mesh.Mesh*) – A mesh.

Returns *fx1* mapping of old face indices to new.

Return type *np.ndarray*

```
entente.shuffle.shuffle_vertices(mesh)
```

Shuffle the mesh’s vertex ordering, preserving the integrity of the faces. The mesh is mutated.

Parameters **mesh** (*lace.mesh.Mesh*) – A mesh.

Returns *vx1* mapping of old vertex indices to new.

Return type *np.ndarray*

1.1.7 entente.testing module

```
entente.testing.assert_same_face_set(a, b)
```

```
entente.testing.assert_same_vertex_set(a, b)
```

```
entente.testing.coord_set(a)
```

```
entente.testing.mesh_asset(*components)
```

```
entente.testing.relative_to_project(*components)
entente.testing.vitra_mesh()
```

1.1.8 entente.trimesh_search module

On Mac OS:

```
brew install spatialindex
pip install rtree trimesh
```

entente.trimesh_search.**faces_nearest_to_points**(*mesh, query_points, ret_points=False*)

Find the triangular faces on a mesh which are nearest to the given query points.

Parameters

- **query_points** (*np.arraylike*) – The points to query, with shape $k \times 3$
- **ret_points** (*bool*) – When *True*, return both the indices of the nearest faces and the closest points to the query points, which are not necessarily vertices. When *False*, return only the face indices.

Returns face indices as $k \times 1$ *np.ndarray*, or when *ret_points* is *True*, a tuple also including the coordinates of the closest points as $k \times 3$ *np.ndarray*.

Return type

entente.trimesh_search.**require_trimesh_with_rtree**()

Check that trimesh and rtree are installed and can be imported, and raise an error with a helpful error message if they are not.

CHAPTER 2

Indices and tables

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